Progress in Dynamic Adversarial Data Collection

Adventures in Multimodal Machine Learning

Douwe Kiela



Hugging Face Stanford University















Alan Turing









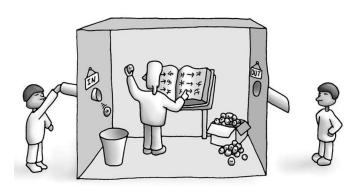


Outline

- 1. Dynabench
 - a. Overview
 - b. Common Objections & Misconceptions
- 2. Progress in Dynamic Adversarial Data Collection
 - a. Humans and Models in Loops
 - b. Dynamic Adversarial Training Data
- 3. Adventures in Multimodal ML
 - a. Evaluation: Hateful Memes, Adversarial VQA, Winoground
 - b. Foundation Models: FLAVA

News / about me...



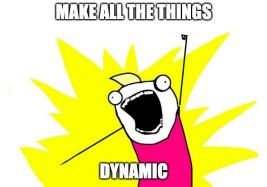


Rethinking benchmarking in Al

Dynabench (<u>dynabench.org</u>) is..

- A research platform.
- A community-based scientific experiment.
- An effort to challenge current benchmarking dogma and help push the boundaries of Al research.

As the name says,





Rethinking Al Benchmarking

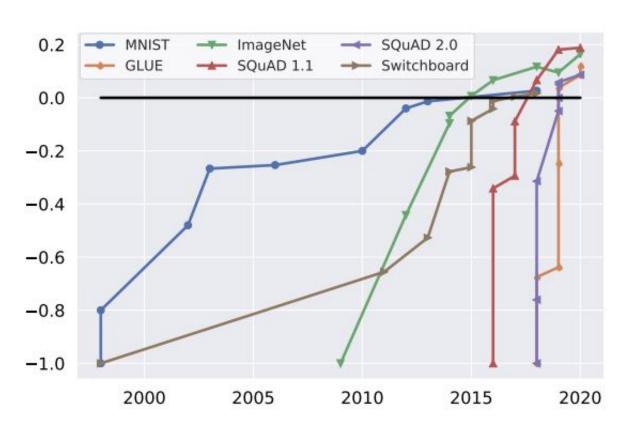
Dynabench is a research platform for dynamic data collection and benchmarking. Static benchmarks have well-known issues: they saturate quickly, are susceptible to overfitting, contain exploitable annotator artifacts and have unclear or imperfect evaluation metrics.

This platform in essence is a scientific experiment: can we make faster progress if we collect data dynamically, with humans and models in the loop, rather than in the old-fashioned static way?



Read more

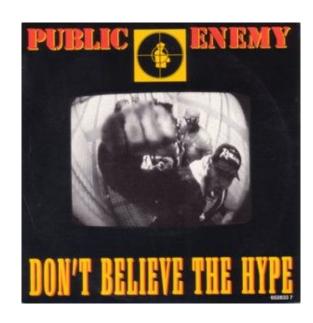
Benchmark saturation in NLP



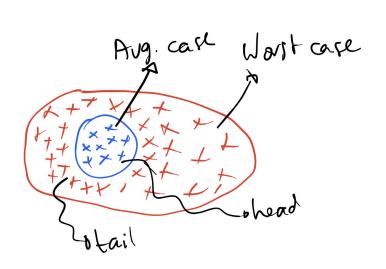
What is our goal? What is language?

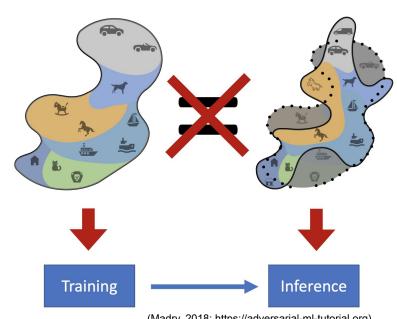
Do believe the hype: we're decent (but not great) at (some) i.i.d. problems when we have enough data and don't care about the worst case.

Don't believe the hype: we are FAR from truly general language understanding that encompasses all of language's recursive, structured, generative, productive, and creative nature.



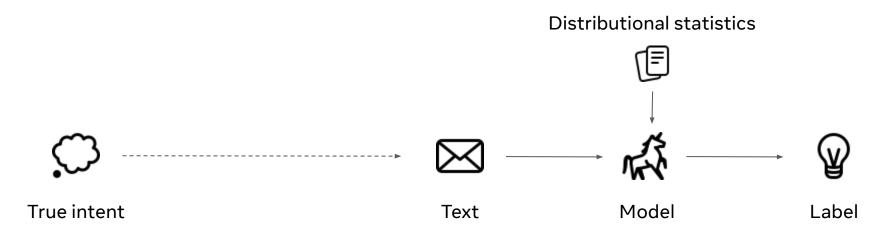
The ability to REALLY understand language

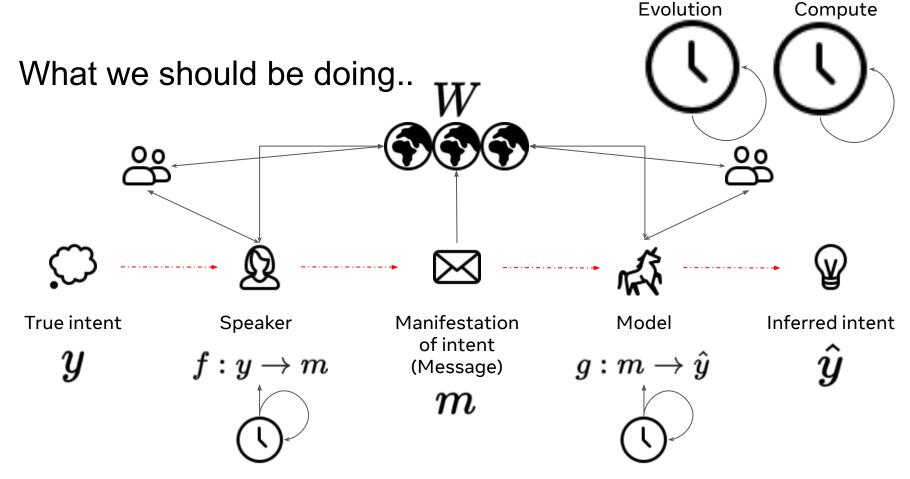




(Madry, 2018; https://adversarial-ml-tutorial.org)

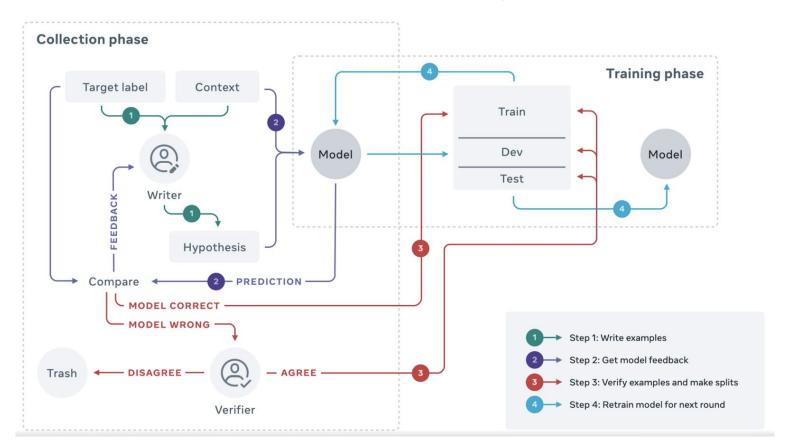
What we are doing...





Measuring not in the average case, but in the worst case.

Dynamic adversarial data collection (ANLI; Nie et al. 2019)



Dynabench goals

Dynabench is a comprehensive benchmarking platform that tackles many well-known problems in benchmarking and model evaluation.

SATURATION

As current benchmarks quickly saturate, the field loses valuable time creating new benchmarks.



BIAS

Inadvertent annotator artifacts and other biases can lead to overfitting.



ALIGNMENT

Test set performance is not always a good proxy for performance in the real-world.



LEADERBOARD CULTURE

Focusing too much on leaderboard rankings hinders creative solutions to AI problems.



REPRODUCIBILITY

Self-reported results cannot be trusted.



ACCESSIBILITY

Models that perform well on current benchmarks are often not easily accessible to the community for probing, let alone to laypeople.



BACKWARD COMPATIBILITY

New benchmark or dataset cannot easily re-evaluate old models on the new data.



UTILITY

Not everyone is optimizing for the same metric. Efficiency might be traded off against accuracy.



Dynabench roles

Live demo

I was served rather the opposite of haute cuisine.

This restaurant was baad!

Summary

Language is about strong generalization. Humans expect this from other linguistic agents. But our systems might be right for the wrong reasons.

Evaluation is broken, we are haunted by Vapnik's ghost but as a field are moving well beyond train-on-train-test-on-test in our deployments of AI (i.e., thanks to large scale pretraining and widely deployed systems).

We need to rethink this. Can we make cyclical progress and do more direct testing with humans in the loop?

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Having all the answers

Dynabench is a research platform that changes over time. It's not about having the right answers, it's about changing the status quo: improving benchmarking will require experimentation.

Adversarialness

Dynabench does not require adversarialness. It's straightforward to collect data with no model in the loop, or with many models in the loop, in an adversarial, collaborative, or other setting.

Language only

Dynabench is not about NLP. It supports many modalities and has tasks in multimodality, vision and (soon) speech. Tasks are currently in English but we'd like to change that.

Cost

Model-in-the-loop data collection can be more expensive, because it requires more creativity. It's still unclear how this cost trades off against data quality - it might be worth it. There are ways to drive the cost down.

Naturalness and distributional shift

Open question how natural the data is, or how natural it will be in the long term.

Being "fair" to the model in the loop

Dynabench aims to measure how well models would hold up if they were deployed "in the wild". The vMER metric is "fair" in that sense for comparing models that were both put in the loop.

Test sets created with a specific model in the loop are not fair to that model. I don't really care about that sort of fairness: a) we could simply put a diverse ensemble of models in the loop; b) we are unfair at a specific point in time, but there will be many more other models to come - this is about measuring these future models.

All rounds count

Dynabench collects data over many rounds. ALL previous rounds, including non-adversarial ones, should be used for testing. An NLI model should perform well on all NLI datasets, adversarial or non-adversarial.

Adversarial filtering

Crowdworkers are paid for every example they generate, including the ones that did not fool any model. Non-model-fooling data is generally not discarded, because it's still useful. Different tasks/datasets filter data in different ways.

Adversarially-collected test sets

- "the constraint that a specified system must fail on the test examples makes it difficult to infer much from absolute measures of test-set performance: As long as a model makes any errors at all on any possible inputs, then we expect it to be possible to construct an adversarial test set against the model, and we expect the model to achieve zero test accuracy on that test set"
 - In Dynabench we advocate for looking at many metrics, including the time it takes a crowdworker to fool a model and how many times a crowdworker needs to try before succeeding (vMER). Not just "did you fool" but also "how easy was it to fool".
 - The errors are not just any kind of error, they are things that humans easily get right and agree on. You need to look at the data itself! (So this reduces to the naturalness objection?)
- "We can further infer that any models that are sufficiently similar to the adversary should also perform very poorly on this test set, regardless of their ability"
 - What about the example of BERT performing below chance on WSC while deBERTa gets 96%? What does "sufficiently similar" mean and who gets to determine that?
 - What about "all models" or "a representative subset of all models"?
- "Neither of these observations would tell us anything non-trivial about the actual abilities of the models" double neg => "These observations only tell us trivial things about the ability of models"
 - That feels a bit strong?

Absolute performance numbers

 "Absolute performance numbers on adversarially-collected test sets are meaningless as measures of model capabilities"

What makes a performance number meaningless? This seems to assume (again) that we haven't looked at the actual data. If a human can easily get the right answer and humans (mostly) agree about a given answer, and the example is natural, why should performance on that example be meaningless?

If this is about naturalness of data, are Turker-collected free-form test sets guaranteed to be more natural?

The scientific process

"significant further work is needed to avoid catastrophe. This will be difficult to achieve without a clear accounting of the abilities and limitations of current and plausible near-future systems"

Exactly this! We should, as a field, work hard to develop a clearer picture of our current capabilities and fix measurement. If we are saturating benchmarks, while we know we have all these issues, something is wrong.

In other words: be careful when you deploy a model and think about what you're doing. We want the world to realize that evaluation is something we should take more seriously. If we can measure better, we can make better progress. This will happen by building on previous work, in cycles of progress where benchmarks "saturate" and are replaced by better once. Science will do its job if we are open to new ideas.

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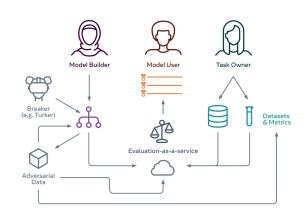
Broader research program

What happens when we put humans and models in loops?

Can we make faster progress? Can we make better measurements?

Can we have fewer biases and artifacts, and better robustness and alignment?

What are we still missing in our models? What are the next challenges to solve?



How can we democratize model evaluation, help make research reproducible, learn from our mistakes as a community, and empower researchers?

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- Vidgen et al. (ACL21). Learning from the Worst: Dynamically Generated Datasets Improve Online Hate Detection
- Potts et al. (ACL21). DynaSent: A Dynamic Benchmark for Sentiment Analysis
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Dataset Papers

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Humans and models in loops

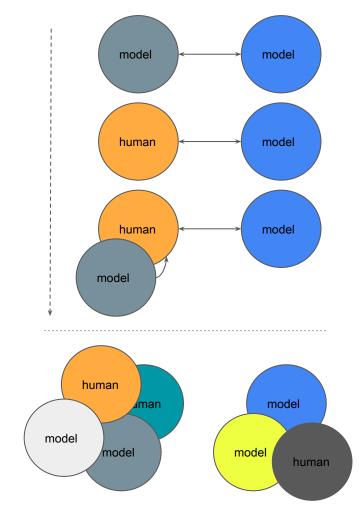
Question 1:

 Instead of human-adversarial, how much can we improve things by just being model-adversarial using human-adversarial data?

Question 2:

 Can generative (adversarial) models help humans fool discriminative models?

Work by **Max Bartolo** et al.



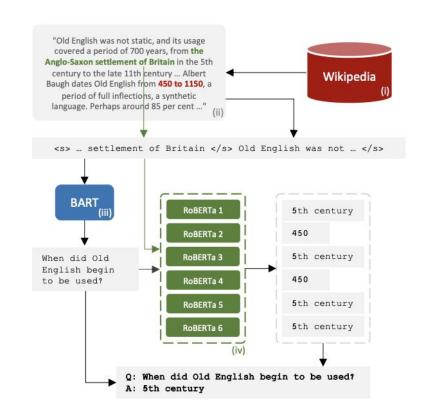
Improving QA robustness with synthetic adversarial data

- Pipeline:
 - 1. Passage selection
 - Answer candidate selection
 - 3. Question generation
 - 4. Filtering and re-labeling
 - 5. Training a new QA model

Improving Question Answering Model Robustness with Synthetic Adversarial Data Generation

Max Bartolo^{†*} Tristan Thrush[‡] Robin Jia[‡] Sebastian Riedel^{†‡}
Pontus Stenetorp[†] Douwe Kiela[‡]

†University College London [‡]Facebook AI Research



Step 2: Answer selection

| Method | #QA pairs | $\mathcal{D}_{	ext{SQuAD}}$ | | $\mathcal{D}_{\mathrm{BiDAF}}$ | | $\mathcal{D}_{\mathrm{BERT}}$ | | $\mathcal{D}_{\mathrm{RoBERTa}}$ | |
|----------------------|--------------|-----------------------------|-------|--------------------------------|-------|-------------------------------|---------|----------------------------------|---------|
| | | EM | F_1 | EM | F_1 | EM | F_{I} | EM | F_{I} |
| POS Extended | 999,034 | 53.8 | 71.4 | 32.7 | 46.9 | 30.8 | 40.2 | 20.4 | 27.9 |
| Noun Chunks | 581,512 | 43.3 | 63.7 | 28.7 | 43.1 | 22.3 | 31.4 | 18.2 | 27.4 |
| Named Entities | 257,857 | 54.2 | 69.7 | 30.5 | 42.5 | 26.6 | 35.4 | 18.1 | 24.0 |
| Span Extraction | 377,774 | 64.7 | 80.1 | 37.8 | 53.9 | 27.7 | 39.1 | 16.7 | 26.9 |
| SAL (ours) | 566,730 | 68.2 | 82.6 | 43.2 | 59.3 | 34.9 | 45.4 | 25.2 | 32.8 |
| SAL threshold (ours) | 393,164 | 68.5 | 82.0 | 46.0 | 60.3 | 36.5 | 46.8 | 24.2 | 32.4 |

Table 2: Downstream test results for a RoBERTa_{Large} QA model trained on synthetic data generated using different answer selection methods combined with a BART_{Large} question generator (trained on SQuAD_{10k} + \mathcal{D}_{AQA}).

Step 3: Question generation

| Method | #QA | $\mathcal{D}_{	ext{SQuAD}}$ | | $\mathcal{D}_{\mathrm{BiDAF}}$ | | $\mathcal{D}_{\mathrm{BERT}}$ | | $\mathcal{D}_{	ext{RoBERTa}}$ | |
|-----------------------------------|---------|-----------------------------|---------|--------------------------------|-------------|-------------------------------|-------------|-------------------------------|-------------|
| Meulou | pairs | EM | F_{l} | EM | F_{I} | EM | F_1 | EM | F_1 |
| R _{SQuAD} | 87,599 | 73.2 | 86.3 | 48.9 | 64.3 | 31.3 | 43.5 | 16.1 | 26.7 |
| $R_{SQuAD+AQA}$ | 117,599 | <u>74.2</u> | 86.9 | <u>57.4</u> | <u>72.2</u> | <u>53.9</u> | <u>65.3</u> | <u>43.4</u> | <u>54.2</u> |
| $\overline{SQuAD_{10k}}$ | 87,598 | 69.2 | 82.6 | 37.1 | 52.1 | 22.4 | 32.3 | 13.9 | 22.3 |
| $\mathcal{D}_{	ext{BiDAF}}$ | 87,598 | 67.1 | 80.4 | 41.4 | 56.5 | 33.1 | 43.8 | 22.0 | 32.5 |
| $\mathcal{D}_{	ext{BERT}}$ | 87,598 | 67.4 | 80.2 | 36.3 | 51.1 | 30.3 | 40.6 | 18.8 | 29.5 |
| $\mathcal{D}_{	ext{RoBERTa}}$ | 87,598 | 63.4 | 77.9 | 32.6 | 47.9 | 27.2 | 37.5 | 20.6 | 32.0 |
| $\mathcal{D}_{	ext{AQA}}$ | 87,598 | 65.5 | 80.1 | 37.0 | 53.0 | 31.1 | 40.9 | 23.2 | 33.3 |
| $SQuAD_{10k} + \mathcal{D}_{AQA}$ | 87,598 | 71.9 | 84.7 | 44.1 | 58.8 | 32.9 | 44.1 | 19.1 | 28.8 |

Table 5: Downstream QA test results using generative models trained on different source data. We compare these results to baseline RoBERTa models trained on SQuAD, and on the combination of SQuAD and AdversarialQA.

Step 4: Filtering and self-training

| Filtering Method | #QA | $\mathcal{D}_{	ext{SQ}}$ | uAD | $\mathcal{D}_{\mathrm{Bi}}$ | DAF | \mathcal{D}_{B} | ERT | $\mathcal{D}_{	ext{RoE}}$ | BERTa |
|--|---------|--------------------------|-------|-----------------------------|---------|----------------------------|-------|---------------------------|---------|
| ratering wethou | pairs | EM | F_1 | EM | F_{I} | EM | F_I | EM | F_{I} |
| Answer Candidate Conf. $(thresh = 0.6)$ | 362,281 | 68.4 | 82.4 | 42.9 | 57.9 | 36.3 | 45.9 | 28.0 | 36.5 |
| Question Generator Conf. $(thresh = 0.3)$ | 566,725 | 69.3 | 83.1 | 43.5 | 58.9 | 36.3 | 46.6 | 26.2 | 34.8 |
| Influence Functions | 288,636 | 68.1 | 81.9 | 43.7 | 58.6 | 36.1 | 46.6 | 27.4 | 36.4 |
| Ensemble Roundtrip Consistency (6/6 correct) | 250,188 | 74.2 | 86.2 | 55.1 | 67.7 | 45.8 | 54.6 | 31.9 | 40.3 |
| Self-training (ST) | 528,694 | 74.8 | 87.0 | 53.9 | 67.9 | 47.5 | 57.6 | 35.2 | 44.6 |
| Answer Candidate Conf. $(thresh = 0.5)$ & ST | 380,785 | 75.1 | 87.0 | 56.5 | 70.0 | 47.9 | 58.7 | 36.0 | 45.9 |

Table 6: Downstream QA test results for different filtering strategies, showing best hyper-parameter settings.

Findings

 Synthetic adversarial data derived from human-adversarial data improves accuracy and robustness.

| Model | Training Data | $\mathcal{D}_{\mathrm{Bi}}$ | $\mathcal{D}_{	ext{BiDAF}}$ | | $\mathcal{D}_{\mathrm{BERT}}$ | | $\mathcal{D}_{\mathrm{RoBERTa}}$ | |
|--------------------|-----------------------------------|-----------------------------|-----------------------------|----------------------------|-------------------------------|----------------------------|----------------------------------|-------|
| Model | II allillig Data | EM | F_{I} | EM | F_1 | EM | F_1 | % |
| R _{SQuAD} | SQuAD | 48.61.3 | 64.2 1.5 | 30.9 1.3 | 43.3 1.7 | 15.8 0.9 | 26.4 1.3 | 20.7% |
| $R_{SQuAD+AQA} \\$ | ↑ + AQA | 59.60.5 | $73.9_{0.5}$ | $54.8_{0.7}$ | $64.8_{0.9}$ | $41.7_{0.6}$ | $53.1_{0.8}$ | 17.6% |
| SynQA | ↑ + SynQA _{SQuAD} | 62.5 0.9 | 76.01.0 | 58.7 1.4 | 68.3 _{1.4} | 46.7 1.8 | 58.0 _{1.8} | 8.8% |
| $SynQA_{Ext}$ | \uparrow + SynQA _{Ext} | 62.7 _{0.6} | 76.2 _{0.5} | 59.0 _{0.7} | 68.9 _{0.5} | 46.8 _{0.5} | 57.8 _{0.8} | 12.3% |

| | | | | | I | MRQA in | -do main | | | | | | | |
|--------------------|----------------------------|----------------------------|----------------------------|---------------------|----------------------|----------------------------|----------------------------|----------------------------|----------------------------|-----------------------|----------------------------|---------------------|------|---------|
| Model | SQ | uAD | New | sQA | Trivi | aQA | Searc | chQA | Hotp | otQA | N | Q | Av | 'g |
| Niouei | EM | F_I | EM | F_I | EM | F_{I} | EM | F_{I} | EM | F_{I} | EM | F_I | EM | F_{I} |
| R_{SQuAD} | 84.1 1.3 | 90.4 1.3 | 41.0 1.2 | 57.5 _{1.6} | 60.20.7 | 69.000.8 | 16.0 1.8 | 20.8 2.7 | 53.60.8 | $68.9_{0.8}$ | 40.5 2.7 | 58.5 2.0 | 49.2 | 60.9 |
| $R_{SQuAD+AQA} \\$ | 84.4 1.0 | 90.2 1.1 | $41.7_{1.6}$ | $58.0_{1.7}$ | 62.7 $_{0.4}$ | 70.8 _{0.3} | $20.6_{2.9}$ | $25.5_{3.6}$ | 56.3 1.1 | $72.0_{1.0}$ | 54.4 0.5 | $68.7_{0.4}$ | 53.3 | 64.2 |
| SynQA | 88.80.3 | 94.3 _{0.2} | 42.9 1.6 | 60.01.4 | 62.3 1.1 | 70.2 1.1 | 23.7 3.7 | 29.54.4 | 59.8 _{1.1} | 75.3 1.0 | 55.1 _{1.0} | 68.7 _{0.8} | 55.4 | 66.3 |
| $SynQA_{Ext} \\$ | 89.0 _{0.3} | 94.3 _{0.2} | 46.2 _{0.9} | $63.1_{0.8}$ | $58.1_{1.8}$ | $65.5_{1.9}$ | 28.7 _{3.2} | 34.3 _{4.1} | $59.6_{0.6}$ | $\textbf{75.5}_{0.4}$ | 55.3 _{1.1} | $68.8_{0.9}$ | 56.2 | 66.9 |
| 8 | 7 | | | | М | QOA out | of domo | in | | | | | | |

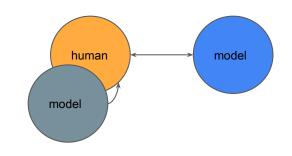
SynQA models are much harder to fool (i.e. more robust)

SynQA outperforms alternatives

MRQA out-of-domain DROP **BioASQ** DuoRC RACE RelationExt. **TextbookQA** Avg Model EMEMEMEMEM $EM F_1$ R_{SQuAD} $53.2_{1.1}$ $68.6_{1.4}$ $39.8_{2.6}$ $52.7_{2.2}$ $49.3_{0.7}$ $60.3_{0.8}$ $35.1_{1.0}$ $47.8_{1.2}$ $74.1_{3.0}$ $84.4_{2.9}$ $35.0_{3.8}$ $44.2_{3.7}$ 47.7 59.7 $R_{SQuAD+AQA}$ $54.6_{1.2}$ $69.4_{0.8}$ $59.8_{1.3}$ $68.4_{1.5}$ $51.8_{1.1}$ $62.2_{1.0}$ $38.4_{0.9}$ $51.6_{0.9}$ $75.4_{2.3}$ $85.8_{2.4}$ $40.1_{3.1}$ $48.2_{3.6}$ 53.3 64.3SynQA **55.1**_{1.5} 68.7_{1.2} 64.3_{1.5} 72.5_{1.7} 51.7_{1.3} 62.1_{0.9} **40.2**_{1.2} **54.2**_{1.3} 78.1_{0.2} 87.8_{0.2} 40.2_{1.3} 49.2_{1.5} **54.9** 65.8 SynQA_{Ext} 54.9_{1.3} 68.5_{0.9} **64.9**_{1.1} **73.0**_{0.9} 48.8_{1.2} 58.0_{1.2} 38.6_{0.4} 52.2_{0.6} **78.9**_{0.4} **88.6**_{0.2} **41.4**_{1.1} **50.2**_{1.0} 54.6 65.1

Empowering crowdworkers with generative assistants

- We know now that generative models trained on adversarial data can help make models more robust.
- Can we use those models to help humans fool models as "generative adversarial assistants"?
 ModelS in the loop!
 - a. Adversarial data is expensive can it be made cheaper?
 - b. Adversarial data can be noisy can it be made higher quality?



Models in the Loop: Aiding Crowdworkers with Generative Annotation Assistants

Max Bartolo* Tristan Thrush[‡] Sebastian Riedel^{‡*}
Pontus Stenetorp* Robin Jia^{†‡} Douwe Kiela[‡]

*UCL [†]USC [‡]Facebook AI Research

Concrete example

A hole is classified by its par, meaning the number of strokes a skilled golfer should require to complete play of the hole. The minimum par of any hole is **3** because par always includes a stroke for the tee shot and **two** putts. Pars of 4 and 5 strokes are ubiquitous on golf courses; more rarely, a few courses feature par-6 and even par-7 holes. Strokes other than the tee shot and putts are expected to be made from the fairway; for example, a skilled golfer expects to reach the green on a par-4 hole in two strokes—one from the...



A: two

Q: How many strokes are needed to make par?





Q: How many putts are considered minimum to make par?



Standard (SDC) vs Adversarial (ADC) Data Collection

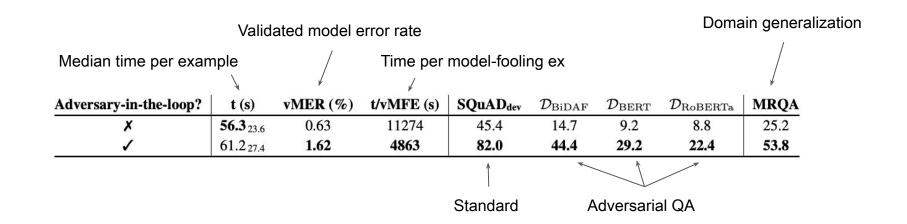
 Earlier finding: "Across a variety of [Question Answering] models and datasets, we find that models trained on adversarial data usually perform better on other adversarial datasets but worse on a diverse collection of out-of-domain evaluation sets." (Divyansh Kaushik et al. ACL 2021)

> On the Efficacy of Adversarial Data Collection for Question Answering: Results from a Large-Scale Randomized Study

Divyansh Kaushik[†], Douwe Kiela[‡], Zachary C. Lipton[†], Wen-tau Yih[‡]

Standard (SDC) vs Adversarial (ADC) Data Collection

New finding:
 (the preliminary take-away on smallish data is – be careful with setup)



Improving SDC

- Using a Generator-in-the-loop makes standard data collection more faster and much higher quality.
- Sampling strategies:
 - a. Likelihood: sample candidates according to the generative model's overall likelihood.
 - b. Adversarial: sample questions according to the lowest F1 score queried against a QA model.
 - c. Uncertainty: select generated questions in order of the least span selection confidence when queried against a QA model.

| Sampling Strategy | t (s) | vMER (%) | t/vMFE (s) | SQuADdev | $\mathcal{D}_{	ext{BiDAF}}$ | $\mathcal{D}_{	ext{BERT}}$ | $\mathcal{D}_{	ext{RoBERTa}}$ | MRQA |
|-------------------|-----------|----------|------------|----------|-----------------------------|----------------------------|-------------------------------|------|
| Likelihood | 40.2 24.8 | 0.69 | 6331 | 53.6 | 15.9 | 11.0 | 9.9 | 31.4 |
| Adversarial | 56.7 23.8 | 3.22 | 2277 | 80.1 | 39.1 | 21.1 | 18.7 | 49.5 |
| Uncertainty | 56.9 25.1 | 2.93 | 2643 | 80.1 | 40.1 | 24.3 | 22.6 | 51.1 |

Improving ADC

- Using a Generator-in-the-loop makes adversarial data collection as fast as standard data collection, with higher quality and better domain generalization.
- Generative Annotation Assistant (GAA) trained on SQuad, AQA or Combined.

| GAA Training | Sampling | t (s) | vMER (%) | t/vMFE (s) | SQuAD _{dev} | $\mathcal{D}_{\mathrm{BiDAF}}$ | $\mathcal{D}_{	ext{BERT}}$ | $\mathcal{D}_{\mathrm{RoBERTa}}$ | MRQA |
|---------------------|-------------|-----------------------------|----------|------------|----------------------|--------------------------------|----------------------------|----------------------------------|------|
| SQuAD | Likelihood | 66.2 31.9 | 2.40 | 3489 | 81.2 | 44.2 | 27.8 | 21.3 | 52.3 |
| SQuAD | Adversarial | 63.3 26.5 | 2.87 | 2831 | 80.2 | 41.7 | 28.8 | 20.9 | 49.3 |
| SQuAD | Uncertainty | 65.7 27.7 | 2.34 | 3505 | 82.6 | 45.1 | 29.0 | 23.0 | 52.4 |
| AdversarialQA | Likelihood | 59.0 26.5 | 2.63 | 3034 | 79.9 | 40.8 | 30.2 | 24.9 | 52.6 |
| AdversarialQA | Adversarial | 64.7 27.4 | 3.95 | 2077 | 75.7 | 38.7 | 28.8 | 23.1 | 50.3 |
| AdversarialQA | Uncertainty | 66.7 28.2 | 3.79 | 2305 | 78.3 | 41.9 | 29.4 | 22.9 | 51.0 |
| Combined | Likelihood | 52.7 _{23.3} | 2.51 | 2827 | 79.6 | 40.7 | 29.9 | 24.2 | 53.3 |
| Combined | Adversarial | 71.0 31.3 | 2.76 | 3450 | 78.7 | 39.8 | 26.6 | 22.0 | 49.6 |
| Combined | Uncertainty | 66.7 26.4 | 3.08 | 2854 | 81.0 | 44.0 | 26.4 | 22.2 | 52.7 |

Improving ADC further

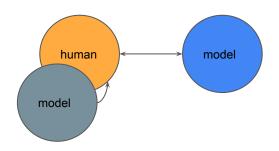
- If you do "answer prompting" where you don't force annotators to pick the answer but suggest one, ADC gets even faster and much higher quality.
- Starting point, traditional data collection: vMER=0.63 with t=56.3
- End point, ADC with GAA: vMER=6.08 with t=43.8

| GAA Training | Sampling | t (s) | vMER (%) | t/vMFE (s) | SQuAD _{dev} | $\mathcal{D}_{\mathrm{BiDAF}}$ | $\mathcal{D}_{	ext{BERT}}$ | $\mathcal{D}_{\mathrm{RoBERTa}}$ | MRQA |
|---------------------|-------------|----------------------|----------|------------|-----------------------------|--------------------------------|----------------------------|----------------------------------|------|
| AdversarialQA | Likelihood | 49.9 29.9 | 6.08 | 1086 | 78.2 | 44.0 | 33.7 | 26.2 | 52.0 |
| AdversarialQA | Adversarial | 43.8 _{22.1} | 2.22 | 2587 | 79.9 | 44.2 | 30.6 | 23.6 | 52.1 |
| AdversarialQA | Uncertainty | 50.9 23.5 | 4.04 | 1667 | 80.4 | 42.8 | 28.8 | 22.1 | 51.1 |
| Combined | Likelihood | 49.0 23.0 | 2.72 | 2510 | 79.6 | 42.7 | 31.1 | 23.8 | 50.2 |
| Combined | Adversarial | 65.2 30.9 | 4.41 | 2042 | 80.2 | 44.7 | 31.5 | 24.8 | 53.0 |
| Combined | Uncertainty | 54.1 22.0 | 2.94 | 2740 | 81.1 | 44.8 | 27.9 | 23.8 | 51.2 |

A "new paradigm"?

ModelS in LoopS:

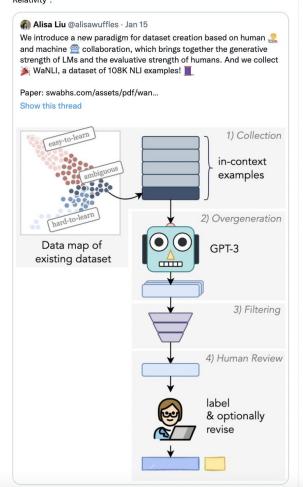
- a. **Yes**, we can collect much higher quality data than static data using this method.
- b. **Yes**, we can collect higher quality data than regular human-and-model-in-the-loop.
- c. Yes, we can do so at a cost that is much lower than human-and-model-in-the-loop matching standard data collection.





Douwe Kiela @douwekiela · Jan 16

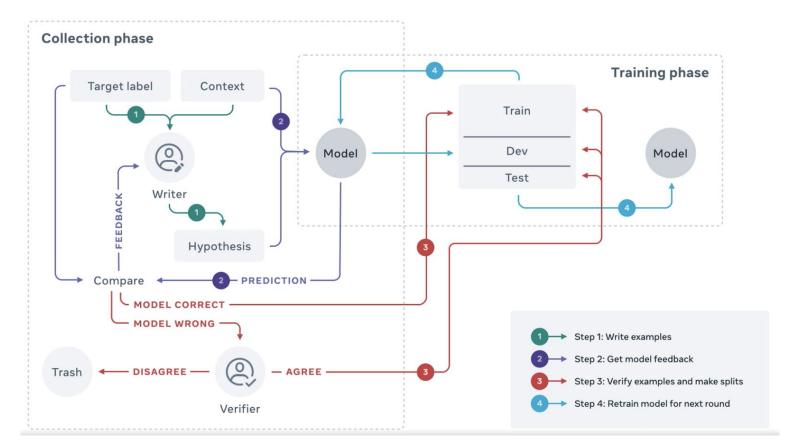
I wish Einstein had done this, it would have been so much easier. "A New Paradigm for Brownian Motion", or "A New (Special/General) Paradigm for Relativity".



Recent work out of the Dynabench team

- Kiela et al. (NAACL21). Dynabench: Rethinking Benchmarking in NLP
- Vidgen et al. (ACL21). Learning from the Worst: Dynamically Generated Datasets to Improve Online Hate Detection
- Potts et al. (ACL21). DynaSent: A Dynamic Benchmark for Sentiment Analysis
- Kirk et al. (2021). Hatemoji: A Test Suite and Dataset for Benchmarking and Detecting Emoji-based Hate
- Sheng & Singh et al. (NeurIPS21). Human-Adversarial Visual Question Answering
- Prasad et al. (Blackbox21). To what extent do human explanations of model behavior align with actual behavior?
- Ma, Ethayarajh, Thrush et al. (NeurlPS21). Dynaboard: A Holistic Evaluation-As-A-Service Benchmarking Platform
- Wenzek et al. (2021). Findings of the WMT 2021 Shared Task on Large-Scale Multilingual Machine Translation
- Thrush et al. (2022). Dynatask: A Platform for Creating Dynamic Al Benchmark Tasks
- Bartolo et al. (EMNLP21). Improving QA Model Robustness with Synthetic Adversarial Data Generation
- Kaushik et al. (ACL21). On the Efficacy of Adversarial Data Collection for Question Answering
- Bartolo et al. (2022). Models in the Loop: Aiding Crowdworkers with Generative Annotation Assistants
- Wallace et al. (2021). Analyzing Dynamic Adversarial Training Data in the Limit

Dynamic adversarial data collection in the limit



Experimental setup

- Starting point: Roberta trained on "All NLI" (MNLI+SNLI+FEVER)
- We hand-construct an expert-curated test set covering a wide range of NLI phenomena.
- We do DADC for 20 rounds (ANLI only did 3).
- We select 10 contexts so that:
 - a. We can afford collecting many rounds of data
 - b. We have some hope of achieving saturation
 - c. We have a broad range of phenomena
 - d. We can create a wide-coverage test set

Work by **Eric Wallace** et al.

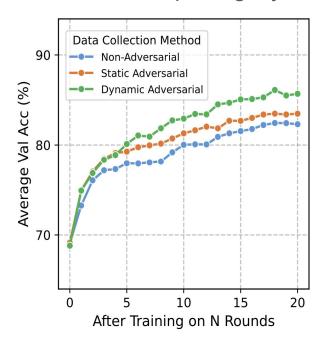
Analyzing Dynamic Adversarial Training Data in the Limit

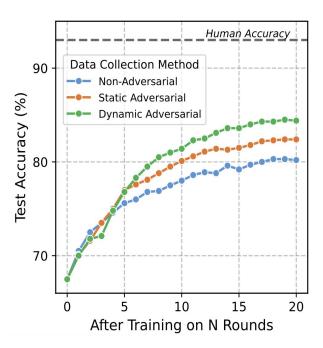
Eric Wallace^{1*} Adina Williams^{2†} Robin Jia^{2,3†} Douwe Kiela^{2†}

¹UC Berkeley ²Facebook AI Research ³USC

Findings: A virtuous cycle

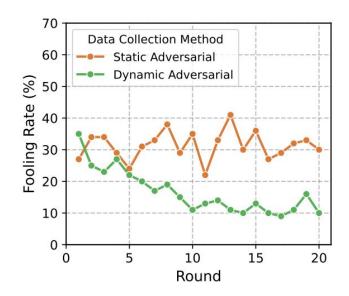
Promising results when exploring Dynamic Adversarial Data Collection in the limit:





Findings: Diversity is key

- DADC data is more diverse, more complex and has fewer artifacts.
- DADC models gets stronger over time.



| | No Model | Static Model | Dynamic Model |
|--------------------|-------------|-----------------|------------------|
| Diversity | | | |
| Unique Unigrams | 4.0k | 4.2k | 4.3k |
| Unique Bigrams | 23.3k | 24.8k | 25.6k |
| Inter-example Sim. | 41.2 | 41.9 | 39.5 |
| Complexity | | | |
| Syntax | 2.0 | 2.1 | 2.3 |
| Reading Level | 4.9 | 5.4 | 5.9 |
| Length | 10.1 | 10.9 | 12.1 |
| Artifacts | | | |
| Hypo-only Acc % | 75.4 | 69.3 | 69.7 |
| Overlap Entail % | 54.2 | 49.2 | 47.3 |

Method take-aways

- ADC looks like a good alternative for traditional crowdworker data collection.
- This is a nice side benefit, considering that the original goal was evaluation.
- Human-and-model-in-the-loop / human feedback holds a lot of promise (see OpenAl's recent papers on this as well, or "red teaming")
- Further work needed on many questions, including:
 - a. How (un)natural is adversarial data and how much does that matter?
 - b. How does dynamic adversarial data collection relate to active learning and continual learning?
 - c. Can we incorporate knowledge about the model in the loop in our optimization procedures?
 - d. Exploring ensembles in the loop, different scoring functions, etc.

What comes next?

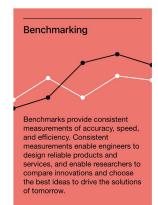
We've opened everything up:

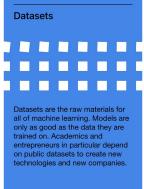
- Fully open source (MIT licensed)
- Dynatask: Anyone can add tasks
- Keep growing the community
- Keep pushing the boundaries
- Exploring synergies with ??



Teaming up with ML Commons and DataPerf

MLCommons aims to answer the needs of the nascent machine learning industry through open, collaborative engineering in three areas:









"Everyone wants to do the model work, not the data work": Data Cascades in High-Stakes Al

Nithya Sambasivan, Shivani Kapania, Hannah Highfill, Diana Akrong, Praveen Paritosh, Lora
Aroyo
[nithyasamba,kapania,hhighfill,dakrong,pkp,loraa]@google.com

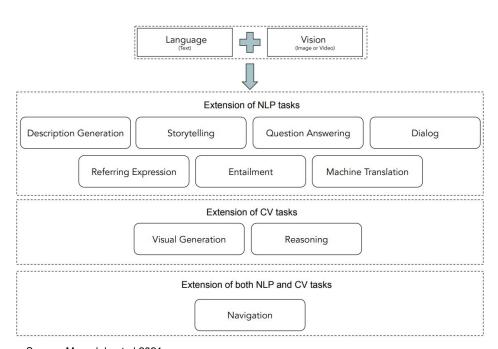
Google Research

Mountain View, CA

Outline

- 1. Dynabench
 - a. Overview
 - b. Common Objections & Misconceptions
- 2. Progress in Dynamic Adversarial Data Collection
 - a. Humans and Models in Loops
 - b. Dynamic Adversarial Training Data
- 3. Adventures in Multimodal ML
 - a. Evaluation: Hateful Memes, Adversarial VQA, Winoground
 - b. Foundation Models: FLAVA

Vision and Language Tasks & Datasets



Source: Mogadala et al 2021

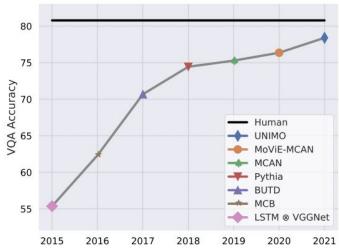
Citations as of 4/4/22:

- VQA/VQA2 3409/1227
- Visual Genome 2776
- COCO 1240 (22724)
- Flickr30k 908
- VisDial 715
- NLVR2 189

Power law distribution with VQA as the dominant task.

Visual Question Answering

VQA is plateauing and arguably/almost saturated





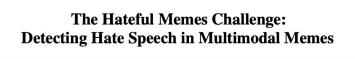


Source: Barbosa-Silva et al 2022

What do we want?

- Ideally, evaluation sets are:
 - High-quality and without error
 - Not too expensive
 - Not too easy
 - Discriminative between models
 - Realistic and representative of practical use-cases
 - Straightforwardly measured
- Multimodal evaluation sets, in addition, ideally are:
 - Not dominated by a specific modality
 - Actually measuring multimodal rather than unimodal performance (cf "making the V in VQA matter")

Multimodal Evaluation



Douwe Kiela, Hamed Firooz, Aravind Mohan,

Vedanuj Goswami, Amanpreet Singh, Pratik Ringshia, Davide Testuggine

NeurIPS 2021

Human-Adversarial Visual Question Answering

Sasha Sheng^{†*} Amanpreet Singh^{†*} Vedanuj Goswami[‡] Jose Alberto Lopez Magana[†]

Wojciech Galuba[‡] Devi Parikh[‡] Douwe Kiela[‡] Facebook AI Research [†] Tecnológico de Monterrey

Winoground: Probing Vision and Language Models for Visio-Linguistic Compositionality

NeurIPS 2020

Tristan Thrush[¶]; Ryan Jiang[‡], Max Bartolo[§],
Amanpreet Singh[¶], Adina Williams[†], Douwe Kiela[¶], Candace Ross^{†*}

¶ Hugging Face; † Facebook AI Research; ‡ University of Waterloo; § University College London

CVPR 2022

Hateful Memes

Motivated by the shortcomings of other V&L datasets: we need something that is harder, more realistic, and requires true multimodal reasoning and understanding.



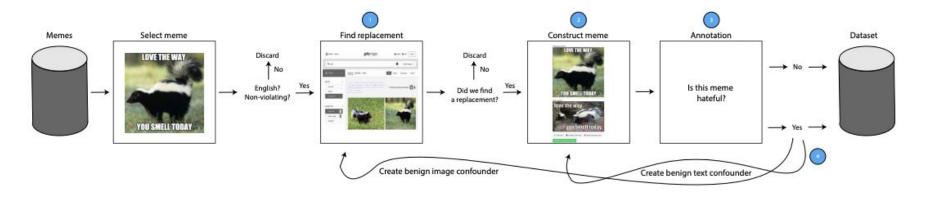
"Mean meme" examples for illustrative purposes – not actually in the dataset

Hateful Memes

Highly trained annotators, so: decent quality but small and expensive

Key concept: benign confounders

A "challenge set" for the community to do zero-shot/finetuning from pretrained



Hateful Memes

Findings in the paper:

- Big gap with human performance.
- Region features
 (as opposed to grid) seem to help.
- Earlier fusion is better than middle,
 Is better than late.
- Multimodal pretraining doesn't really work.

| | | Vali | idation | Te | est |
|--------------------------|------------------|-------|---------|------------------|------------------|
| Type | Model | Acc. | AUROC | Acc. | AUROC |
| | Human | - | | 84.70 | = |
| | Image-Grid | 50.67 | 52.33 | 52.73±0.72 | 53.71±2.04 |
| Unimodal | Image-Region | 52.53 | 57.24 | 52.36 ± 0.23 | 57.74 ± 0.73 |
| | Text BERT | 58.27 | 65.05 | 62.80 ± 1.42 | 69.00 ± 0.11 |
| | Late Fusion | 59.39 | 65.07 | 63.20±1.09 | 69.30±0.33 |
| | Concat BERT | 59.32 | 65.88 | 61.53 ± 0.96 | 67.77 ± 0.87 |
| Multimodal | MMBT-Grid | 59.59 | 66.73 | 62.83 ± 2.04 | 69.49 ± 0.59 |
| (Unimodal Pretraining) | MMBT-Region | 64.75 | 72.62 | 67.66±1.39 | 73.82 ± 0.20 |
| (Ommodai Fiedaming) | Vilbert | 63.16 | 72.17 | 65.27±2.40 | 73.32 ± 1.09 |
| | Visual BERT | 65.01 | 74.14 | 66.67±1.68 | 74.42 ± 1.34 |
| Multimodal | ViLBERT CC | 66.10 | 73.02 | 65.90±1.20 | 74.52±0.06 |
| (Multimodal Pretraining) | Visual BERT COCO | 65.93 | 74.14 | 69.47±2.06 | 75.44 ± 1.86 |

Hateful Memes Competition

After the paper came a \$100k competition on an unseen test set:

| Type | Model | Unse Acc. | een Dev AUROC | Unsee Acc. | n Test AUROC |
|--|---|--|--|--|---|
| Unimodal | Image-Region Text BERT | 61.48 60.37 | 53.54 60.88 | $ \begin{array}{c c} 60.28 \pm 0.18 \\ 63.60 \pm 0.54 \end{array} $ | 54.64 ± 0.80 62.65 ± 0.40 |
| Multimodal (Unimodal Pretraining) | Late Fusion Concat BERT MMBT-Grid MMBT-Region ViLBERT Visual BERT | 61.11 64.81 67.78 70.04 69.26 69.67 | 61.00 65.42 65.47 71.54 72.73 71.10 | 64.06 ± 0.02 65.90 ± 0.82 66.85 ± 1.61 70.10 ± 1.39 70.86 ± 0.70 71.30 ± 0.68 | 64.44 ± 1.60 66.28 ± 0.66 67.24 ± 2.53 72.21 ± 0.20 73.39 ± 1.32 73.23 ± 1.04 |
| Multimodal (Multimodal Pretraining) | ViLBERT CC Visual BERT COCO | 70.37 70.77 | 70.78 73.70 | 70.03 ± 1.07 69.95 ± 1.06 | 72.78 ± 0.50 74.59 ± 1.56 |

| # | Team | AUROC | Acc. |
|---|--------------------|----------|--------|
| 1 | Ron Zhu | 0.844977 | 0.7320 |
| 2 | Niklas Muennighoff | 0.831037 | 0.6950 |
| 3 | Team HateDetectron | 0.810845 | 0.7650 |
| 4 | Team Kingsterdam | 0.805254 | 0.7385 |
| 5 | Vlad Sandulescu | 0.794321 | 0.7430 |

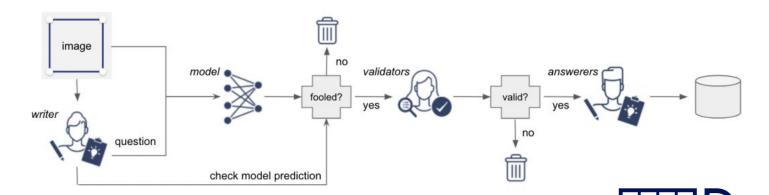
Winner characteristics: frameworks matter, SOTA pretrained models, ensembles, entities, faces and external knowledge.

STILL FAR FROM SOLVED.

Adversarial VQA

HM is not perfect and everybody loves VQA, can we improve VQA itself?

First multimodal approach to human-and-model-in-the-loop, dynamic adversarial data collection:



Adversarial VQA

Is VQA as a task really arguably/ almost saturated?

No. Not even close (with simple questions):

| | Model | VQA test-dev | AdVQA test | VQA | AdVQA val |
|--------------------------|------------------------------|-----------------|---------------|-------|--------------|
| Humar | ı performance | 80.78 | 91.18 | 84.73 | 87.53 |
| Majority | answer (overall) | - | 13.38 | 24.67 | 11.65 |
| Majority answ | ver (per answer type) | - | 27.39 | 31.01 | 29.24 |
| Model in loop | MoViE+MCAN [42] | 73.56 | 10.33 | 73.51 | 10.24 |
| TT-desertal | ResNet-152 [20] | 26.37 | 10.85 | 24.82 | 11.22 |
| Unimodal | BERT [13] | 39.47 | 26.9 | 39.40 | 23.81 |
| Multimodal | MoViE+MCAN* [42] | 71.36 | 26.64 | 71.31 | 26.37 |
| (unimodal pretrain) | MMBT [28] | 58.00 | 26.70 | 57.32 | 25.78 |
| (ummodai pictram) | UniT [22] | 64.36 | 28.15 | 64.32 | 27.55 |
| | VisualBERT [33] | 70.37 | 28.70 | 70.05 | 28.03 |
| | Vilbert [39] | 69.42 | 27.36 | 69.27 | 27.36 |
| Multimodal | ViLT [30] | 64.52 | 27.11 | 65.43 | 27.19 |
| (multimodal pretrain) | UNITER _{Base} [10] | 71.87 | 25.16 | 70.50 | 25.20 |
| | UNITER _{Large} [10] | 73.57 | 26.94 | 72.71 | 28.03 |
| | VILLA _{Base} [16] | 70.94 | 25.14 | 69.50 | 25.17 |
| | $VILLA_{Large}$ [16] | 72.29 | 25.79 | 71.40 | 26.18 |
| Multimodal | M4C (TextVQA+STVQA) [23] | 32.89 | 28.86 | 31.44 | 29.08 |
| unimodal pretrain + OCR) | M4C (VQA v2 train set) [23] | 67.66 | 33.52 | 66.21 | 33.33 |

VQA AdVQA Image



Q: How many cats are in the image? A: 2 Model: 2, 2, 2

Q: What brand is the tv? A: lg Model: sony, samsung, samsung

Q: How many cartoon drawings

are present on the cat's tie?



Q: Does the cat look happy? A: no

A: 4 Model: no, no, no **Model**: 1, 1, 2

Q: What kind of floor is the man sitting on? A: wood

A: no Model: wood, wood, wood Model: yes, yes, yes

Q: Did someone else take this picture?

Adversarial VQA

Table 4: The category-wise performance of VQA models. The state-of-the-art VQA models perform very close to the majority class prior, illustrating the challenge and difficulty of AdVQA.

| Model | Question Type yes/no numbers others | | | |
|----------------|---|-------|-------|--|
| Majority Class | 62.28 | 31.11 | 9.29 | |
| ResNet-152 | 62.81 | 0.18 | 0.51 | |
| BERT | 67.58 | 26.87 | 9.25 | |
| VisualBERT | 55.51 | 32.29 | 17.66 | |
| Vilbert | 55.58 | 29.49 | 16.67 | |
| MoViE+MCAN* | 52.74 | 33.62 | 14.56 | |
| M4C (VQA2) | 56.67 | 38.04 | 22.73 | |

Table 5: The category-wise distribution of answers. Compared to VQA, AdVQA contains more "number" based and lesser "yes/no" questions supporting the prior work's observations around failure of VQA models to count and read text.

| Question Type | VQA test-dev | AdVQA test | VQA | AdVQA val |
|------------------|-----------------|---------------|-------|------------------|
| yes/no | 38.36 | 17.89 | 37.70 | 17.90 |
| number | 12.31 | 41.91 | 11.48 | 31.80 |
| others | 49.33 | 40.20 | 50.82 | 50.30 |

AdVQA & AVQA

More information: adversarialvqa.org

Adversarial VQA: A New Benchmark for Evaluating the Robustness of VQA Models

adversarialvqa.github.io

Linjie Li¹, Jie Lei², Zhe Gan¹, Jingjing Liu³

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Adversarial VQA Home People Download Evaluation

What is Adversarial VQA?

Adversarial VQA is a new VQA benchmark that is collected with Human-And-Model-in-the-Loop for evaluating the robustness of state-of-the-art VQA systems.

- · 2 datasets: AdVQA (in-domain) and AVQA (out-of-domain)
- Collected in single round or multiple rounds
- 81,253 images (COCO/Conceptual Captions 3M/Fakeddit/VCR)
- 1.9 human-verified adversarial questions on average per image
- 10 ground truth human-written answers per verified question

Dataset

Details on downloading the latest dataset may be found on the download webpage.

August 2021: Full release (v1.0)

AdVQA (In-domain)

- · Collected in single round
- 41,807 COCO images (only for val/test)
- 46,807 questions
- 468,070 human-written answers

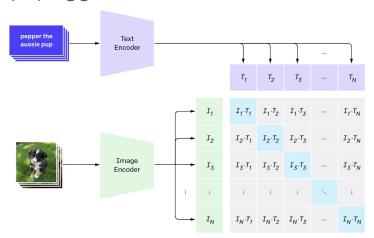
AVQA (Out-of-domain)

- · Collected with 3 rounds
- 40,637 images from Conceptual Captions/ Fakeddit/VCR (for train/val/test)
- 104,410 verified questions, 73,075 unverified questions
- 1,044,100 human-written answers for verified questions, 73,075 VQA model answers for unverified questions

STILL FAR FROM SOLVED.

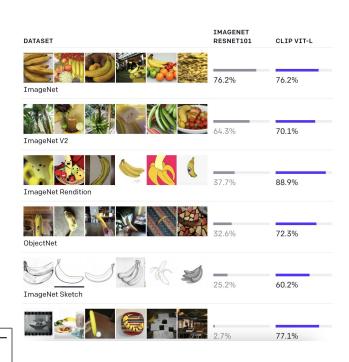
Winoground

CLIP (re)triggered interest in multimodality



Learning Transferable Visual Models From Natural Language Supervision

Alec Radford * 1 Jong Wook Kim * 1 Chris Hallacy 1 Aditya Ramesh 1 Gabriel Goh 1 Sandhini Agarwal 1 Girish Sastry 1 Amanda Askell 1 Pamela Mishkin 1 Jack Clark 1 Gretchen Krueger 1 Ilya Sutskever 1



Winoground

But how good is CLIP really?

Some relevant ideas/findings from NLP:



(a) some plants surrounding a lightbulb



(b) a lightbulb surrounding some plants

- Winograd schemas
 "The [trophy] doesn't fit in the [suitcase] because it is too [large/small]"
- Word order may not matter all that much

Masked Language Modeling and the Distributional Hypothesis: Order Word Matters Pre-training for Little

Koustuv Sinha^{†‡} Robin Jia[†] Dieuwke Hupkes[†] Joelle Pineau^{†‡}
Adina Williams[†] Douwe Kiela[†]

Winoground

- Examples written by linguist experts
- Using Getty Images API
- Simple way to measure by comparing scores
- In some cases, very difficult and requiring world knowledge







[some grass]

(a) there is [a mug] in (c) a person [sits] and a

dog [stands]

(e) it's a [truck] [fire]









there is some grass] in [a mug]

(d) a person [stands] and a dog [sits]

(f) it's a [fire] [truck]



Relation

Both









magnifying looks at them []

(a) the kid [with the (c) the person with the (e) there are [three] ponytail [packs] stuff people and [two] winand other [buys] it









(b) the kid [] looks at (d) the person with the them [with the magnifying glass]

ponytail [buys] stuff and other [packs] it

(f) there are [two] people and [three] windows

Pragmatics

Series

Symbolic

Winoground Findings

- SOTA models often perform below chance (again).
- VinVL/UNITER/ViLLA perform best, probably because they're trained with image-text matching (ITM) loss.
- Paper has a breakdown by category, and shows that these models probably fall back to a weak unimodal prior.

| Model | Text | Image | Group |
|--------------------------------|-------|-------|-------|
| MTurk Human | 89.50 | 88.50 | 85.50 |
| Random Chance | 25.00 | 25.00 | 16.67 |
| VinVL | 37.75 | 17.75 | 14.50 |
| $UNITER_{large}$ | 38.00 | 14.00 | 10.50 |
| $UNITER_{base}$ | 32.25 | 13.25 | 10.00 |
| $ViLLA_{large}$ | 37.00 | 13.25 | 11.00 |
| ViLLA _{base} | 30.00 | 12.00 | 8.00 |
| VisualBERT _{base} | 15.50 | 2.50 | 1.50 |
| ViLT (ViT-B/32) | 34.75 | 14.00 | 9.25 |
| LXMERT | 19.25 | 7.00 | 4.00 |
| $ViLBERT_{base}$ | 23.75 | 7.25 | 4.75 |
| $UniT_{ITMfinetuned}$ | 19.50 | 6.25 | 4.00 |
| CLIP (ViT-B/32) | 30.75 | 10.50 | 8.00 |
| VSE++ _{COCO} (ResNet) | 22.75 | 8.00 | 4.00 |
| $VSE++_{COCO}(VGG)$ | 18.75 | 5.50 | 3.50 |
| $VSE++_{Flickr30k}$ (ResNet) | 20.00 | 5.00 | 2.75 |
| $VSE++_{Flickr30k}$ (VGG) | 19.75 | 6.25 | 4.50 |
| VSRN _{COCO} | 17.50 | 7.00 | 3.75 |
| ${\sf VSRN}_{Flickr30k}$ | 20.00 | 5.00 | 3.50 |

STILL FAR FROM SOLVED.

Outline

- 1. Dynabench
 - a. Overview
 - b. Common Objections & Misconceptions
- 2. Progress in Dynamic Adversarial Data Collection
 - a. Humans and Models in Loops
 - b. Dynamic Adversarial Training Data
- 3. Adventures in Multimodal ML
 - a. Evaluation: Hateful Memes, Adversarial VQA, Winoground
 - b. Foundation Models: FLAVA

Building pretrained multimodal models - why?

- Many tasks are multimodal: the internet and the world are multimodal
- Modalities can complement each other and share knowledge and resources
- Sharing parameters and improved sample efficiency
- Architectures are overly domain specific (slowly changing with Transformers taking over everything)
 - so we may require N models for N tasks
- Modality-agnostic large language models
 => foundation models.

On the Opportunities and Risks of Foundation Models

Rishi Bommasani* Drew A. Hudson Ehsan Adeli Russ Altman Simran Arora Sydney von Arx Michael S. Bernstein Jeannette Bohg Antoine Bosselut Emma Brunskill Erik Brynjolfsson Shyamal Buch Dallas Card Rodrigo Castellon Niladri Chatterji Annie Chen Kathleen Creel Jared Quincy Davis Dorottya Demszky Chris Donahue Moussa Doumbouya Esin Durmus Stefano Ermon John Etchemendy Kawin Ethayarajh Li Fei-Fei Chelsea Finn Trevor Gale Lauren Gillespie Karan Goel Noah Goodman Shelby Grossman Neel Guha Tatsunori Hashimoto Peter Henderson John Hewitt Daniel E. Ho Jenny Hong Kyle Hsu Jing Huang Thomas Icard Saahil Jain Dan Jurafsky Pratyusha Kalluri Siddharth Karamcheti Geoff Keeling Fereshte Khani Omar Khattab Pang Wei Koh Mark Krass Ranjay Krishna Rohith Kuditipudi Ananya Kumar Faisal Ladhak Mina Lee Tony Lee Jure Leskovec Isabelle Levent Xiang Lisa Li Xuechen Li Tengyu Ma Ali Malik Christopher D. Manning Suvir Mirchandani Eric Mitchell Zanele Munyikwa Suraj Nair Avanika Narayan Deepak Narayanan Ben Newman Allen Nie Juan Carlos Niebles Hamed Nilforoshan Julian Nyarko Giray Ogut Laurel Orr Isabel Papadimitriou Joon Sung Park Chris Piech Eva Portelance Christopher Potts Aditi Raghunathan Rob Reich Hongyu Ren Frieda Rong Yusuf Roohani Camilo Ruiz Jack Ryan Christopher Ré Dorsa Sadigh Shiori Sagawa Keshav Santhanam Andy Shih Krishnan Srinivasan Alex Tamkin Rohan Taori Armin W. Thomas Florian Tramèr Rose E. Wang William Wang Bohan Wu Jiajun Wu Yuhuai Wu Sang Michael Xie Michihiro Yasunaga Jiaxuan You Matei Zaharia Michael Zhang Tianyi Zhang Xikun Zhang Yuhui Zhang Lucia Zheng Kaitlyn Zhou

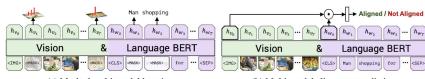
Challenges

- Paired cross-modal data is not abundantly available
- Data from prior work has not been made public
- Joint learning across modalities is hard
- Pretraining techniques are domain specific
- Unclear how to leverage unimodal data

Compute



derestimate the potential of this line of research. To address this, we constructed a new dataset of 400 million (image, text) pairs collected form a variety of publicly available sources on the Internet. To attempt to cover as broad a set of visual concepts as possible, we search for (image, text) pairs as part of the construction process whose text includes one of a set of 500,000 queries.¹ We approximately class



(a) Masked multi-modal learning

(b) Multi-modal alignment prediction

FLAVA

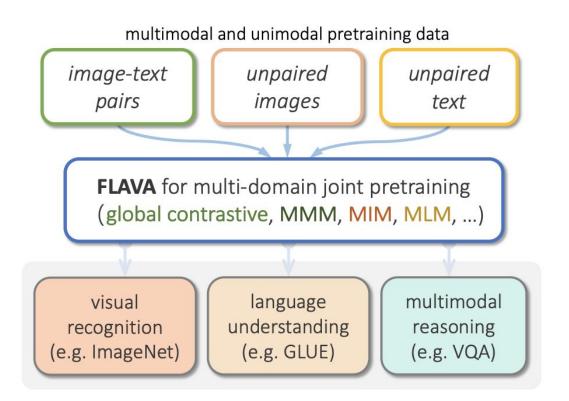
- Holistic approach to multimodality
- One foundation model spanning V&L, CV and NLP



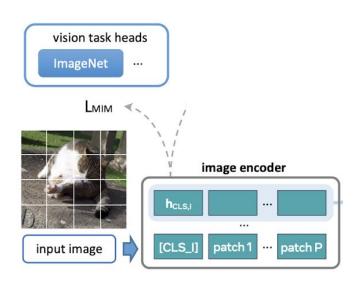
- Jointly pretrained on:
 - unimodal text data (CCNews + BookCorpus)
 - unimodal image data (ImageNet)
 - public paired image-text data (70M)
- All data/models are publicly released



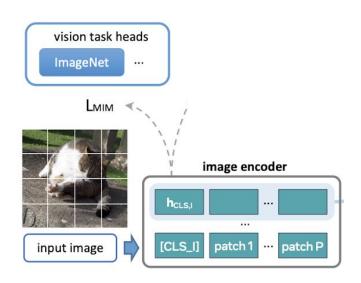
The problem to solve

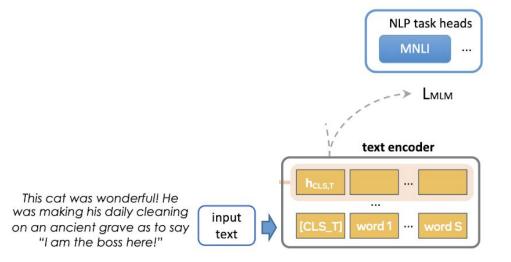


How does FLAVA work?

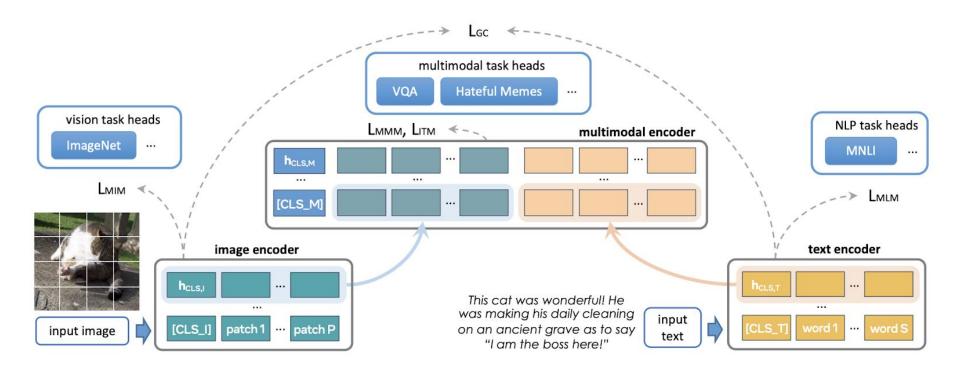


How does FLAVA work?





How does FLAVA work?



The PMD dataset

70M image-text pairs from public sources

COCO

TO THE PARTY OF TH

A close up view of a pizza sitting on a table with a soda in the back.

Visual Genome



a lenovo laptop Front view of basket rebooting 13, from the sidewalk in front of the basket.

SBU captions



ket walk t ket. u

Localized narratives



The woman is touching a utensil in front of her on the grill stand.

WIT



Typocerus balteatus, Subfamily: Flower Longhorns

RedCaps



Deigdoh falls in india

CC12M



Jumping girl in a green summer dress stock illustration

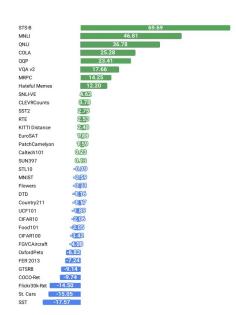
YFCC filtered



In the kitchen at the Muse Nissim de Camondo

How well does it work?

On average, over 35 tasks,
 FLAVA obtains impressive performance



| | | MIM 1 | MLM 2 | FLAVA _C | $FLAVA_{MM}$ 4 | FLAVA w/o init 5 | FLAVA 6 | CLIP 7 | CLIP 8 |
|-----------------------|-------------|----------|----------|--------------------|----------------|---------------------|--------------|-----------|--------------|
| Datasets | Eval method | PMD | PMD | PMD | PMD | (PMD+IN-1k+CC | 5815.1 | PMD | 400M [83] |
| MNLI [111] | fine-tuning | 1 - | 73.23 | 70.99 | 76.82 | 78.06 | 80.33 | 32.85 | 33.52 |
| CoLA [110] | fine-tuning | _ | 39.55 | 17.58 | 38.97 | 44.22 | 50.65 | 11.02 | 25.37 |
| MRPC [29] | fine-tuning | _ | 73.24 | 76.31 | 79.14 | 78.91 | 84.16 | 68.74 | 69.91 |
| QQP [49] | fine-tuning | _ | 86.68 | 85.94 | 88.49 | 98.61 | 88.74 | 59.17 | 65.33 |
| SST-2 [97] | fine-tuning | _ | 87.96 | 86.47 | 89.33 | 90.14 | 90.94 | 83.49 | 88.19 |
| QNLI [88] | fine-tuning | - | 82.32 | 71.85 | 84.77 | 86.40 | 87.31 | 49.46 | 50.54 |
| RTE [7, 25, 36, 40] | fine-tuning | _ | 50.54 | 51.99 | 51.99 | 54.87 | 57.76 | 53.07 | 55.23 |
| STS-B [1] | fine-tuning | _ | 78.89 | 57.28 | 84.29 | 83.21 | 85.67 | 13.70 | 15.98 |
| NLP Avg. | | - | 71.55 | 64.80 | 74.22 | 75.55 | <u>78.19</u> | 46.44 | 50.50 |
| ImageNet [90] | linear eval | 41.79 | - | 74.09 | 74.34 | 73.49 | 75.54 | 72.95 | 80.20 |
| Food101 [11] | linear eval | 53.30 | - | 87.77 | 87.53 | 87.39 | 88.51 | 85.49 | 91.56 |
| CIFAR10 [58] | linear eval | 76.20 | - | 93.44 | 92.37 | 92.63 | 92.87 | 91.25 | 94.93 |
| CIFAR100 [58] | linear eval | 55.57 | - | 78.37 | 78.01 | 76.49 | 77.68 | 74.40 | 81.10 |
| Cars [56] | linear eval | 14.71 | - | 72.12 | 72.07 | 66.81 | 70.87 | 62.84 | 85.92 |
| Aircraft [74] | linear eval | 13.83 | - | 49.74 | 48.90 | 44.73 | 47.31 | 40.02 | 51.40 |
| DTD [20] | linear eval | 55.53 | | 76.86 | 76.91 | 75.80 | 77.29 | 73.40 | 78.46 |
| Pets [79] | linear eval | 34.48 | - | 84.98 | 84.93 | 82.77 | 84.82 | 79.61 | 91.66 |
| Caltech101 [32] | linear eval | 67.36 | - | 94.91 | 95.32 | 94.95 | <u>95.74</u> | 93.76 | 95.51 |
| Flowers 102 [76] | linear eval | 67.23 | - | 96.36 | 96.39 | 95.58 | 96.37 | 94.94 | <u>97.12</u> |
| MNIST [60] | linear eval | 96.40 | _ | 98.39 | 98.58 | 98.70 | 98.42 | 97.38 | 99.01 |
| STL10 [21] | linear eval | 80.12 | _ | 98.06 | 98.31 | 98.32 | 98.89 | 97.29 | 99.09 |
| EuroSAT [41] | linear eval | 95.48 | _ | 97.00 | 96.98 | 97.04 | <u>97.26</u> | 95.70 | 95.38 |
| GTSRB [100] | linear eval | 63.14 | _ | 78.92 | 77.93 | 77.71 | 79.46 | 76.34 | 88.61 |
| KITTI [35] | linear eval | 86.03 | _ | 87.83 | 88.84 | 88.70 | <u>89.04</u> | 84.89 | 86.56 |
| PCAM [106] | linear eval | 85.10 | _ | 85.02 | 85.51 | <u>85.72</u> | 85.31 | 83.99 | 83.72 |
| UCF101 [98] | linear eval | 46.34 | - | 82.69 | 82.90 | 81.42 | 83.32 | 77.85 | 85.17 |
| CLEVR [52] | linear eval | 61.51 | - | 79.35 | <u>81.66</u> | 80.62 | 79.66 | 73.64 | 75.89 |
| FER 2013 [38] | linear eval | 50.98 | - | 59.96 | 60.87 | 58.99 | 61.12 | 57.04 | <u>68.36</u> |
| SUN397 [113] | linear eval | 52.45 | - | 81.27 | 81.41 | 81.05 | 82.17 | 79.96 | 82.05 |
| SST [83] | linear eval | 57.77 | - | 56.67 | 59.25 | 56.40 | 57.11 | 56.84 | 74.68 |
| Country211 [83] | linear eval | 8.87 | - | 27.27 | 26.75 | 27.01 | 28.92 | 25.12 | 30.10 |
| Vision Avg. | | 57.46 | | 79.14 | 79.35 | 78.29 | 79.44 | 76.12 | 82.57 |
| VQAv2 [39] | fine-tuning | - | - | 67.13 | 71.69 | 71.29 | 72.49 | 59.81 | 54.83 |
| SNLI-VE [114] | fine-tuning | 0-0 | - | 73.27 | 78.36 | 78.14 | 78.89 | 73.53 | 74.27 |
| Hateful Memes [53] | fine-tuning | | - | 55.58 | 70.72 | <u>77.45</u> | 76.09 | 56.59 | 63.93 |
| Flickr30K [81] TR R@1 | | - | - | 68.30 | 69.30 | 64.50 | 67.70 | 60.90 | 82.20 |
| Flickr30K [81] TR R@5 | | - | - | 93.50 | 92.90 | 90.30 | 94.00 | 88.90 | 96.60 |
| Flickr30K [81] IR R@1 | zero-shot | - | - | 60.56 | 63.16 | 60.04 | 65.22 | 56.48 | 62.08 |
| Flickr30K [81] IR R@5 | zero-shot | _ | - | 86.68 | 87.70 | 86.46 | 89.38 | 83.60 | 85.68 |
| COCO [66] TR R@1 | zero-shot | _ | - | 43.08 | 43.48 | 39.88 | 42.74 | 37.12 | 52.48 |
| COCO [66] TR R@5 | zero-shot | _ | - | 75.82 | 76.76 38.46 | 72.84 | <u>76.76</u> | 69.48 | 76.68 |
| COCO [66] IR R@1 | zero-shot | _ | _ | 37.59 | 38.46 | 34.95 | 38.38 | 33.29 | 33.07 |
| COCO [66] IR R@5 | zero-shot |) == : | - | 67.28 | 67.68 | 64.63 | 67.47 | 62.47 | 58.37 |
| Multimodal Avg. | | | - | 66.25 | 69.11 | 67.32 | 69.92 | 62.02 | 67.29 |
| Macro Avg. | | 19.15 | 23.85 | 70.06 | 74.23 | 73.72 | <u>75.85</u> | 61.52 | 66.78 |

How well does it work?

| Experimental setting | vision-only tasks | vision-and-language tasks | | language-only tasks (GLUE benchmark) | | | | |
|--|----------------------|------------------------------|---------------------|--------------------------------------|----------------------|------------------|-----------------|-------------------|
| | ImageNet accuracy | VQAv2 accuracy | SNLI-VE accuracy | HM AUROC | QNLI accuracy | MNLI accuracy | QQP accuracy | SST-2 accuracy |
| FLAVA one pretrained model shared between tasks | 75.5 | <u>72.8</u> | <u>79.0</u> | <u>76.7</u> | 87.3 | 80.3 | 90.4 | 90.9 |
| UniT one model shared between tasks | - | 67.0 | 73.1 | - | 88.0 | 80.9 | 90.6 | 89.3 |
| VisualBERT (Li et. al.) separately fine-tuned on each task | - | 70.8 | 77.3 | 74.1 | 87.0 | 81.6 | 89.4 | 89.4 |
| CLIP (Radford et. al.) | <u>80.2</u> | 55.3 | 73.5 | 56.6 | 50.5 | 33.5 | 76.8 | 88.2 |
| BERT (Devlin et. al.) separately fine-tuned on each task | - | - | - | - | <u>91.0</u> | <u>84.4</u> | 90.6 | <u>92.4</u> |

What's next?

- Always work in progress
- Challenges we addressed:
 - Data => PMD
 - Architecture => Transformers
 - Joint training => FLAVA
 - Requires heavy compute
- Things to explore:
 - Fully sharing (almost) all parameters
 - Training bigger models on more data
 - Training on all the modalities

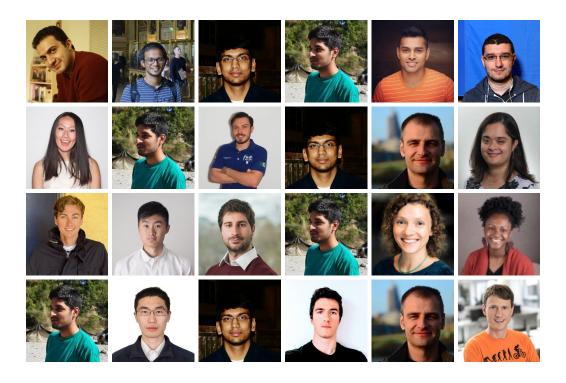
How about closing the loop?

We're still working on the FLAVA open source release.
 Preliminary results on Winoground (WG) and AdVQA:

| | WG-Text | WG-Image | WG-Group | <u>AdVQA</u> |
|-------|---------|----------|----------|--------------|
| Best | 37.75 | 17.75 | 14.50 | 33.67 |
| FLAVA | 32.25 | 19.75 | 14.00 | 36.02 |

I don't want to underhype but.. There is more work to be done!

Thanks multimodal collaborators



Thanks Dynabench collaborators











Who is on the team?

Everyone! People who have contributed to Dynabench so far include: Douwe Kiela, Divyansh Kaushik, Max Bartolo, Adina Williams, Yixin Nie, Grusha Prasad, Pratik Ringshia, Amanpreet Singh, Robin Jia, Sebastian Riedel, Tristan Thrush, Atticus Geiger, Chris Potts, Pontus Stenetorp, Mohit Bansal, Bertie Vidgen, Zeerak Talat, Zhiyi Ma, Ledell Wu, Sonia Kris, Zen Wu, Kawin Ethayarajh, Alberto Lopez, Sasha Sheng, Eric Wallace, Pedro Rodriguez, Rebecca Qian, Somya Jain, Guillaume Wenzek, Sahir Gomez, Anmol Gupta, Hannah Rose Kirk, Zoe Papakipos, Kok Rui Wong, Ishita Dasgupta, Anand Rajaram, Fatima Zahra Chriha, and others.

Thanks for listening

Questions?